Application of Robotic Therapy

Upper Limb Training

for

Stroke Patients



DORIS LAM

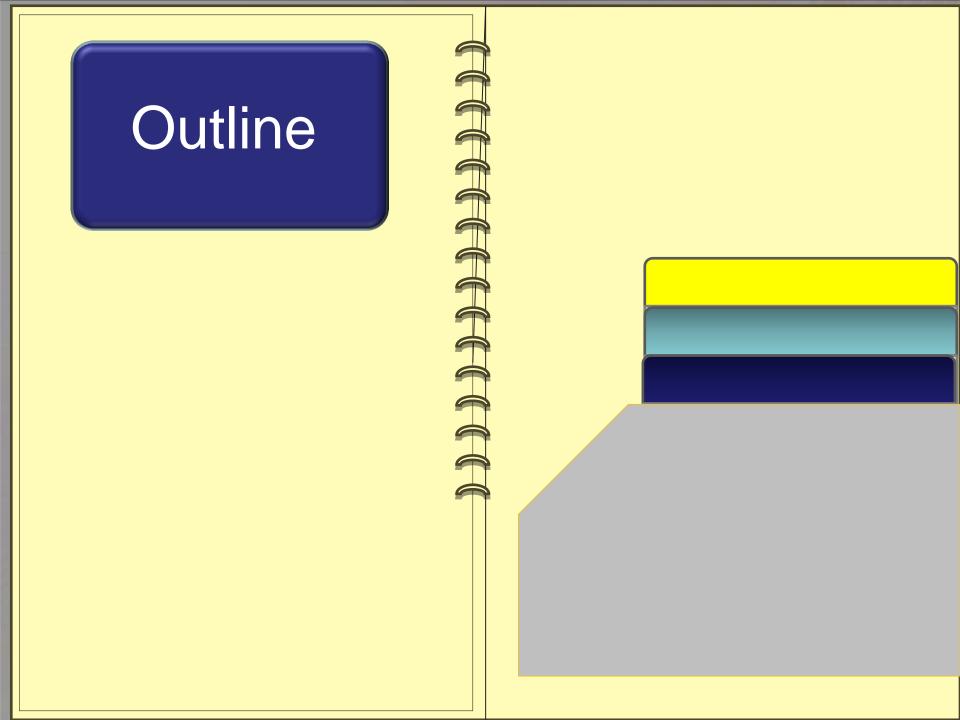
Occupational Therapist I

Occupational Therapy Department, Tuen Mun Hospital

Hospital Authority

Hong Kong





Stroke Rehabilitation

 A major health issue in Hong Kong Entails various degrees of motor and functional deficits, adversely affecting survivors' community living and quality of life

Functional training of the paretic limbs has been a focus

 Majority (70-80%) of stroke survivors fail to attain full recovery in the paretic arm (Khandare et al, 2013)



Evidence-Canadian Best Practice Recommendation for stroke Care (2012)

1

Stroke patients should receive through an individualized treatment plan, a minimum of 3 hours of direct task-specific therapy for a minimum of 5 days per week (Evidence Level A)

2)

Repetitive & intense task-oriented therapy is effective in promoting recovery in both acute and late phase of stroke rehabilitation (Evidence Level A).

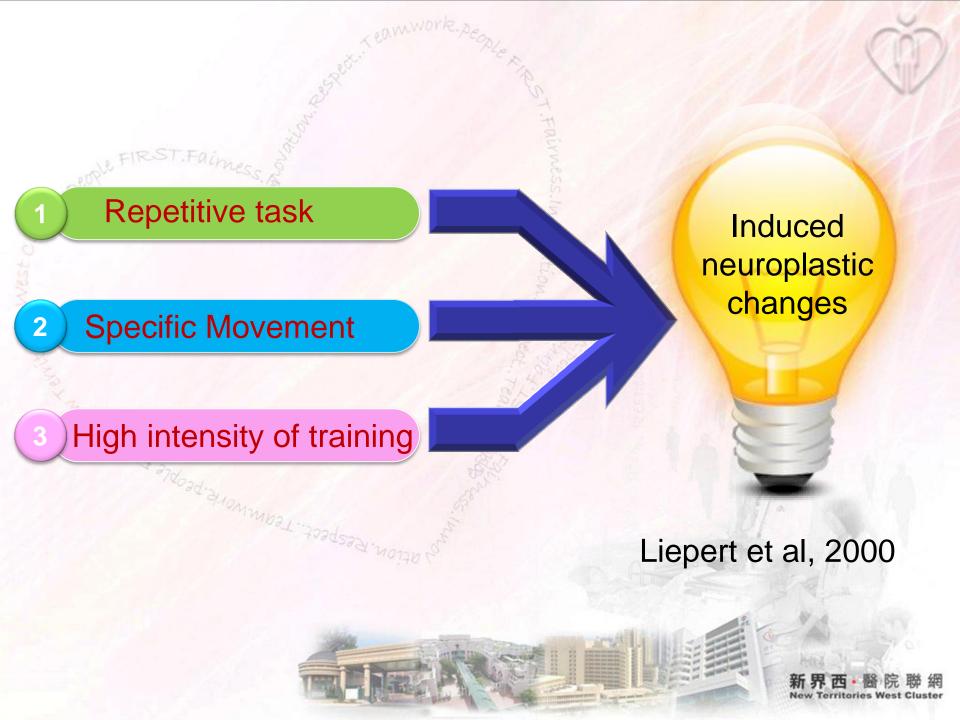


Higher intensity in terms of longer, more frequent training is associated with better rehabilitation outcomes.



There is strong (Level 1a) evidence that repetitive task specific training techniques improve measures of upper extremity function.





Neuroplasticity / brain Plasticity

Definition: The capability of the brain to reorganize by forming new neural connections throughout life.

- It allows the neurons in the brain to compensate for injury and disease and to adjust their activities in response to new situations or to change in the environment (*Dr. H. El Sharkawy*)
- Motor recovery programs should include meaningful, repetitive, intensive and taskspecific movement training in an enriched environment to promote neural plasticity (*T Nao & Shin*, 2013)





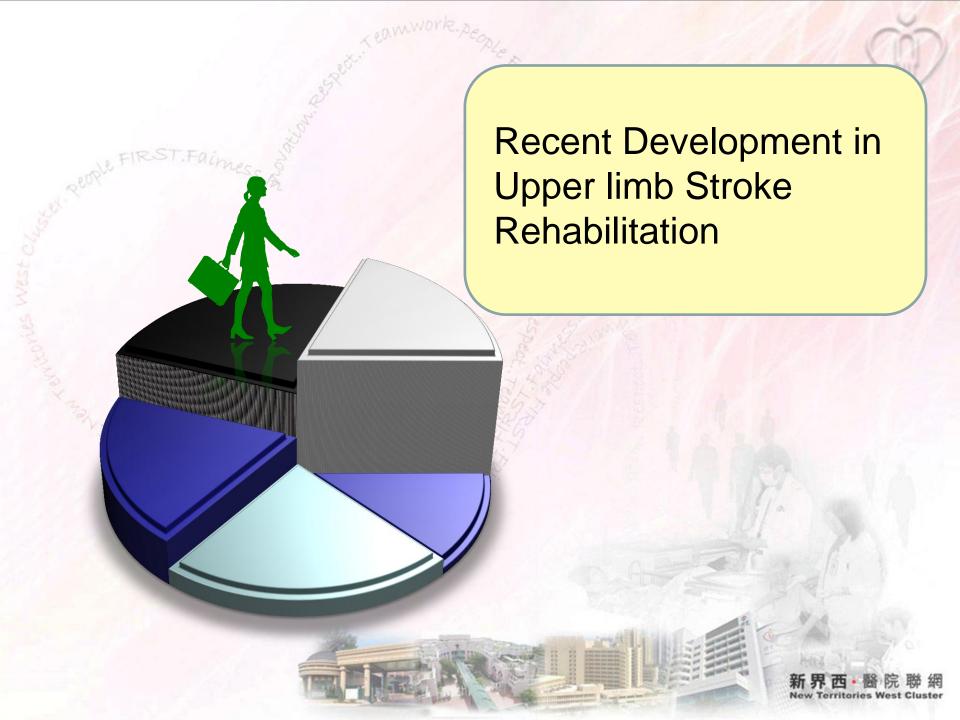
Upper Limb Training: OT Approach

Conventional
Rehabilitation
Training for Paretic
upper limb



Advanced
Technology
Rehabilitation
Training for paretic
upper limb



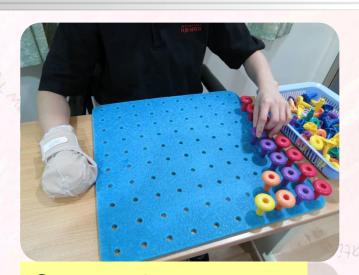


Evidence - EBRSR: 10. Upper Extremity Intervention

Norine Foley MSc, Robert Teasell MD, Jeffrey Jutai PhD CPsych, Sanjit Bhogal MSc, Elizabeth Kruger

1

Constraint-induced movement therapy is a beneficial treatment approach for those stroke patients with some active wrist and hand movement.



Constraintinduced Therapy



Evidence - EBRSR: 10. Upper Extremity Intervention

Norine Foley MSc, Robert Teasell MD, Jeffrey Jutai PhD CPsych, Sanjit Bhogal MSc, Elizabeth Kruger

There is preliminary evidence that virtual reality therapy may improve motor outcomes post stroke

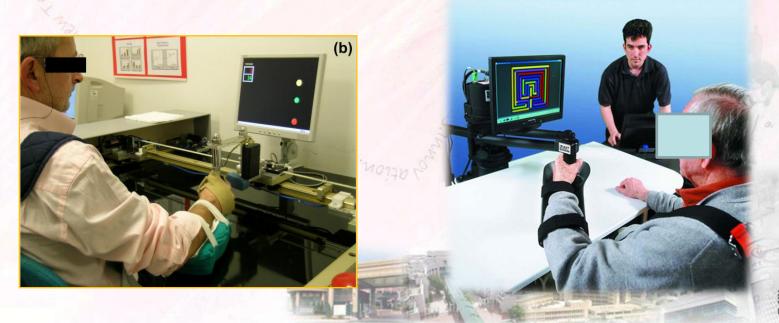


Evidence - EBRSR: 10. Upper Extremity Intervention

Norine Foley MSc, Robert Teasell MD, Jeffrey Jutai PhD CPsych, Sanjit Bhogal MSc, Elizabeth Kruger

Sensorimotor training with robotic devices improves functional and motor outcomes of the shoulder and elbow.

Last updated July 2012 www.ebrsr.com



Robotic Therapy



Robotic Therapy in Upper Extremity

An upper limb robotic therapy in rehabilitation is an external device that assists or guides movement with the intention of improving function

Presents virtual reality (VR) games and tasks to the patient that can be adjusted to level of ability, interest and specific movement problems



Theoretical Benefit of Robots Therapy in Upper Extremity

Point 1 Robot will allow the patient to achieve a task

Point 2 Repetitive goal orientated practice requiring attention

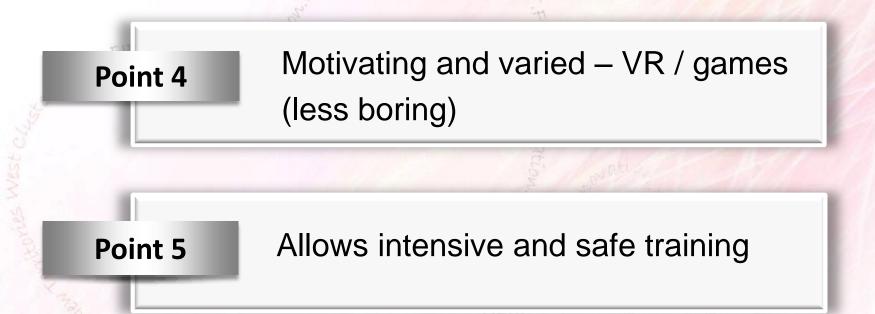
Tasks can be adjusted to provide success at the limit of performance

Point 3

Jane Burridge, 2013



Theoretical Benefit of Robots Therapy in Upper Extremity



Point 6 Appropriate for all levels of ability

Jane Burridge, 2013



Theoretical Benefit of Robots Therapy in Upper Extremity

Point 7

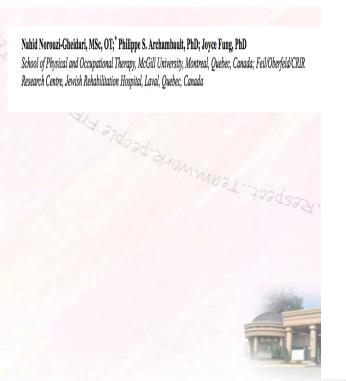
Robotics is an area of interest in stroke rehabilitation

Several studies have reported improvements in strength and motor function with robotic treatment (Burgar, Lum, Shor, & Machiel Van der Loos, 2000; Finley et al., 2005).



Effects of robot-assisted therapy on stroke rehabilitation in upper limbs: Systematic review and meta-analysis of the literature

Volume 49, Number 4, 2
Pages 479–496
(2012)



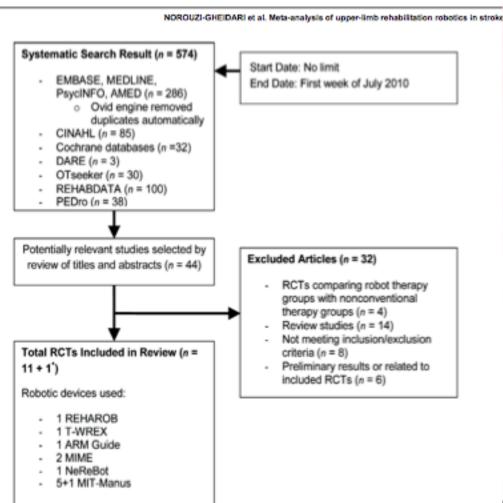


Table 1. Characteristics of selected randomized controlled trials

Study		Sex)		e (yr) SD (Range) CT	Months/[wes Poststi Mean ± SD c	roke	Stroke Stage at Admission	Robotic Device	Outcome Measures o Interest
azekas et al. [1]		15 (10/5)*	56.6 ± ?	55.9 ± ?	23.2 ± 7	9.5 ± ? (1.1–44)	Not Stated (Subscute/ Chronic)	REHAROB	F-M (s/e), FIM (self- care)
lousman et						112.4±128.5	Chronic	T-WREX	F-M (UL)
Sahn et s	Co	nvei	ntior	ial		103.1 ± 48.2	Chronic	ARM Guide	Ch-McM (arm)
um et al. [4		Ther	apv			28.8 ± 6.3	Chronic	MIME	F-M (UL), FIM (self- care)
um et al. [5						[10.62.7]wk	Subscute	MIME	F-M (UL), FIM (self- care), MSS MPS
fasiero et al. [6]	17 (10/7)	18 (11/7)	63.4±11.		[≤l week]	[≤l week]	Acute	NeReBot	F-M (s/e/e, w/h), FIM (self-care)
vison et al. [7] ⁸	10 (5/5)	10 (6/4)	58.5 ± 8.3	• • V	4.13vk	[3.34.2]wk	Acute	MIT-Manus	F-M (UL), FIM (self- care), MSS MPS
blpe et al. [8] [§]	6 (4/2)	6 (3/3)	54 ± 7.3	66					M (s/e/c, b), FIM Geare), MPS
bipe et al. [9]	30 (16/14)	26 (14/12)6	2 ± 11	R	obotic	Assi	sted		M (s/e/c, b), FIM otor), SS, MPS
olpe et al. [10]	11 (8/3)	10 (7/3)	52 ± 3	60	Thera	ару			M (s/e/e, b), MPS
tabadi et al. [11]	10 (5/5)	10 (5/5)	79.5 ± 6.3	2:					M (UL), uM (motor MSS, MPS
o et al. [12] [¶]	49 (47/2)	50 (48/2) 6 28 (27/1)	6 ± 11 (44–95)	64 ± 11 (28–86) 63 ± 12 (42–88)	3.6 ± 4.0 (0.6–19.8)	4.8 ± 4.0 (0.5–15.7) 6.2 ± 5.0 (0.5–23.6)	Chronic	MIT-Marrus	F-M (UL)

Result

Point 1

When the duration/intensity of conventional therapy is matched with the robot-assisted therapy, no difference in motor recovery, ADL, strength, and motor control.

Point 2

Extra session of robotic therapy in addition to regular therapy are more beneficial than regular therapy alone



Local Experience in Robotic Therapy for Stroke Patients





Armeo Power



ReoGo



Application of Robotic Therapy in Upper Limb



Exoskeleton Device Gravity-supported UL Exercise

Computer enhanced upper limb exercise, task relevance and feedback

Functional Activities









Properties of the selected exercise



- Parameters
- Difficulty level
- > Time limit
- Repetitions
- > Autogrip
- Autowrist



Local Studies Sharing

- Tuen Mun Hospital
 Occupational Therapy Department
- Cowloon Hospital Occupational Therapy Department
- Caritas Medical Centre
 Occupational Therapy Department



Robotic Training Program in Tuen Mun Hospital

Rehabilitation Stroke Unit

Inclusion Criteria

Principal diagnosis in stroke

The Functional Test for the Hemiplegic Upper Extremity (Hong Kong) Level II to level VI

Exclusion Criteria:

MAS score for shoulder and elbow equal or more than 2

Pilot Study in Tuen Mun Hospital

Rehabilitation Stroke Unit



Time: February 2010 to July 2011



Number of subject: 41



Intervention: Conventional Therapy + Robotic therapy



Outcome measure: The Functional Test for the Hemiplegic Upper Extremity (Hong Kong) FTHUE



Result



32 Subjects have increased FTHUE level.



FTHUE level II to level IV patients showed greatest improvement among different groups of upper limb level after completing the Robotic Arm Training

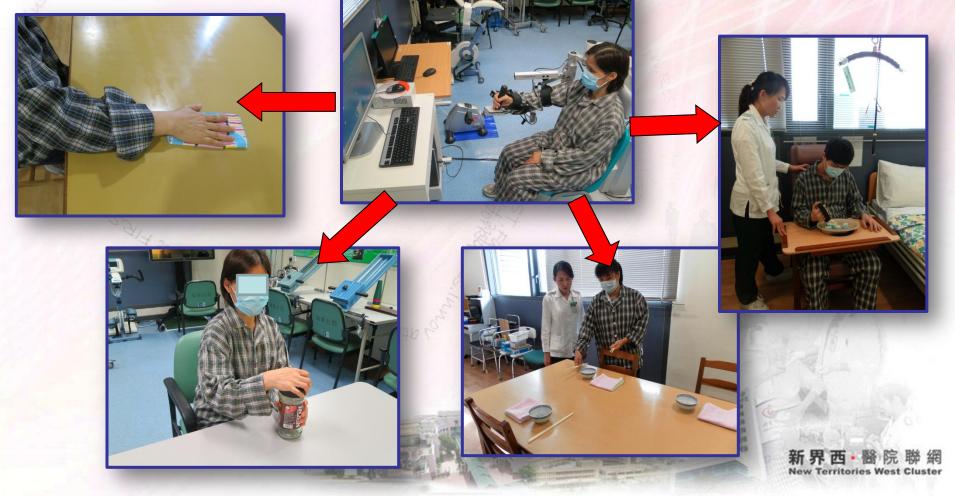


Program Implementation

Attend training session 5 days per week

Duration: 30 minutes Armeo Spring training and functional





A Associated	Level 2	R. Deople	Functional Activities
reactions		2	Rain Mug (1D)
B Hand into lap		T. T.	Vegetable Grater (1D)
C Arm clearance	Level 3		Jump(1D)
during shirt tuck		50	Snow Balls (1D)
D Hold a pouch		nova	Stove Cleaning (2D)
E Stabilize a jar	Level 4	tion	Window Mopping (2D)
F Simulated			William Wopping (22)
wringing a rag			Fish Catching(2D)
G Blocks and Box	Level 5	36.5	Fruit Shopping (2D)
H Eat with a spoon		#5	Egg Cracking (2D)
I Box on Shelf	Level 6		Flower Watering (2D)
J Drink from glass			Popping Air Bubbles (2D)
K Key turning	Level 7		Picnic (2D)
L1 Use chopsticks			Reveal Panorama (3D)
(dominant hand)			Reveal Picture (3D)
L2 Clip cloth peg (non			` ,
dominant hand)		The second second	Chase Ballon (3D)

Local Studies Sharing – Caritas Medical Centre

N	26
Sex	Male=8 (31%)
Age	77.85±10.85
Hemi	Right =11 (43%)
No. of sessions	6.3 (average)

N=26	Pre	Post	P value
N=20	FIE	PUSI	r value
FM Score	49.00 (±18.16)	55.57 (±15.64)	0.002
UE	29.69 (±9.99)	32.04 (±7.81)	0.027
Wrist	6.19 (±3.94)	7.31 (±3.61)	0.005
Hand	9.38 (±5.16)	11.27 (±4.68)	0.004
Coordination	4.19 (±1.26)	4.84 (±1.41)	0.000
FTHUE	4.85 (±1.99)	5.69 (±1.76)	0.008
MBI	51.35 (±18.88)	64.27 (±17.76)	0.014

Patients More Engaged & Motivated Patients

gainentertainment

					Cumulative		
	١	Frequency	Percent	Valid Percent	Percent		
Valid	.00.	7	16.3	16.3	16.3		
	2.00	4	9.3	9.3	25.6		
	3.00	12	27,9	27.9	53.5		
	4.00	20	46.5	46.5	100.0		
	Total	43	100.0	100.0			

eniovment

	enjoyment								
					Cumulative				
		Frequency	Percent	Valid Percent	Percent				
al.	.00	10	23.3	23.3	23.3				
:	2.00	2	4.7	4.7	27.9				
	3.00	11	25.6	25.6	53.5				
	4.00	20	46.5	46.5	100.0				
	Total	43	100.0	100.0					

satis

		Frequency	Percent	Valid Percent	Cumulative Percent
Valid	C)O.	7	16.3	16.3	16.3
	3.(00	8	18.6	18.6	34.9
:	4.00	28	65.1	65.1	100.0
	Total	43	100.0	100.0	

геlах

relax							
					Cumulative		
		Frequency	Percent	Valid Percent	Percent		
Valid	.00	7	16.3	16.3	· 16.3		
	2.00	4	9.3	9.3	25.6		
	3.00	14	32.6	32.6	58.1		
	4.00	18	41.9	41.9	100.0		
	Total	43	100.0	100.0			

Source: Caritas Medical Centre

The Efficacy of Robotic Therapy on Improving Hemiplegic Upper Limbs Function by Using a Stratified Protocol of the Armeo Robotic Devices

Kowloon Hospital

Objectives:

(1)To develop a treatment protocol based on Armeo Robotic Therapy, that benefit the stroke patients at different levels of upper limb function (FTHE-HK)

(2) To test the pre and post treatment intervention effect on patients based on (1)



- 48 subjects and classified into three treatment groups.
- According to the level of Functional Test for the Hemiplegic Upper Extremity.
- Group 1 is functional level 2.
- Group 2 is functional level 3 and 4.
- Group 3 is functional level 5 and 6.
- The outcome measures includes Fugl Meyer Assessment, grip power and the data gathered from the robotic device.



Training modules for Group 1 : UL functional level 2

Minimum Motion of the level 2						
Some beginning voluntary motion of the shoulder and elbow						
Therapy Plan with autogrip on, total 45 min. program						
Game	Workspace	Level	Time			
Rain Mug Vegetable Grater Window mopping Stove cleaning Popping air	1D 1D 2D (frontal plane) 2D (hori. plane) 2D (frontal plane)	4 level 4 level V easy & easy & medium V easy & easy & medium Easy	3 min @ 3 min @ 3 min @ 3 min @ 3 min			

Training Modules for Group 2: UL functional level 3-4

Minimum Motion of the level						
Level 3		30-60° shoulder flexion 60-100° elbow flexion 3-5lb gross grasp				
Level 4		>60° shoulder flexion, > 100° elbow flexion and some extension, 3-5lb gross grasp,1/2 – 3 lb lateral pinch				
Therapy Plan with autogrip on, 45 min session						
Game	Game Workspace		Level	Time		
Rain Mug		1D	Hard	3 min		
Vegetable Grat	er	1D	Hard	3 min		
Window		2D (frontal)	Easy & Medium & hard	3 min @		
Mopping 2D		2D (frontal)	V. easy & easy & medium	3 min @		
Fruit shopping		2D (frontal)	V. easy & easy & medium	3 min @		
Egg Cracking		2D (horizontal)	Easy & Medium & hard	3 min @		

Medium

3 min

Stove Cleaning

Fish catching

2D (frontal)

Training Modules for Group 3: UL functional level 5-6

Minimum Motion	Minimum Motion of the level					
Level 5	Mass flexion and extension combination pattern of shoulder and elbow >5lb of grasp >3lb of lateral pinch some release					
Level 6	Isolated control in the shoulder, elbow & wrist against gravity >5lb of grasp >3lb of lateral pinch					

Therapy Plan with autogrip off, 45 min

Game	Workspace	Level	Time
Rain mug	1D	Hard	3 min
Vegetable	1D	Hard	3 min
Grater	2D (frontal)	Easy	3 min
Flower	2D (frontal)	Easy	3 min
watering	2D (horizontal)	Medium &	3 min @
Popping air	3D (functional	hard	3 min @
bubble	ex.)	Medium &	3 min @
Stove	3D (functional	hard	3 min @
cleaning	ex.)	Medium&	3 min @
Reveal	3D (functional	hard	1.min @
Panorama	ex.)	Medium&	
Chase Balloon	3D (game)	hard	
Shelf	2D (game)	Medium&	
Goal Keeper		hard	
Moonhuhu		Medium	

Paired T-Test (Post-Tx /3 wk after Tx with Pre-Tx)

yet. ?	FMA UL	FMA Hand	S Flexion	S Abd	E Flexion	Supinati on	Pronati on	Grip
Gp1	.000/.000	.001/.001	.000/.000	.001/.002	.011/.012	.004/.004	.067/.001	.010/.004
Gp2	.000/.003	.000/.001	.000/.033	.000/.021	.056/.209	.000/.019	.000/.003	.000/.003
Gp3	.025/.007	.002/.001	.109/.025	.247/.476	.678/.672	.001/.000	.082/.033	.319/.316

All have significant difference in FMA by T-test

Change of AROM <u>not sig.</u> in proximal joints for <u>gp3</u>, as indicated in RED

The gain of AROM is more sig. in gp1 and gp 2





中風病人上肢康復治療新法

實驗關不限的甲輕人世界。 更有助中原病人由上跌患律 治療 - 九陳 賴於利用 62 22 首 光平利泉北市4月38分、高北市全部 定植较等。加上皮質與實際 数等声得观力法十四里音道 TO LIBERTURE - DESCRIPTION DESCRIPTION 日本市口山市の土田内世界 所由国际宣 更农人的建进 **唐华琳娅·施**波引大病存已 和班子老中提供人學家。

经专工我想好

・ 関係のは現在するを含くされる。 ABBURER OFFICER EL **加州: 为何人上把各位保存的第一件** SHOW HERE IN THE PARTY OF THE PARTY. 目前] - 於學的第十個想 - U.E. : 計算 子供の知識様の研究とこの方が開発機 刘启帝一等《宣传号张史教》及《播榜 #14- 市价[有用从科研性活動方便 **拉下奶的塔向针增新生!**。

高层整套公理技术工具屏幕 - 进 **新校里原教给你的审问的做、螺旋**员 最级白板技物影響一切專與較大能響

【本報訊】電子及進縮度 前·前回(音音)·宣4多 ★日本 林州 / 中文中用图和电子等 - 水果银行 **建筑形型化上层层板 - 照可在底层底** (付資保工・部署銀行代及協等・衛衛 我人应衷时, 张功士放对领内证。

患者右手双锁七式

RESERVED AND DESCRIPTION OF THE PARTY NAMED IN COLUMN TWO IS NOT THE PARTY NAMED IN COLUMN TWO IS NAMED IN COLUMN TWO IS N **必知可犯上放江水小市、新印度附屬** 首、公司監管事件は同じ元年代一会 传手艺术是这人提示, 改善土民法则 報理事功能と組入課的委託とは平中 能成若手不能提高。最初只须是殊技 斯提伯德 - 医中国价值市场规划 / 1 经 NUMBER OF SHIPP STARK 当有切位置、自且「看好我吃、最供



体恐惧者自由恐怕病 人在用其由地原具引力操

陈下、京都某一村京都 好成本問題、古述暫定日

STOR

B1016

NO.

以大大田 M GIBU

智尔加速型补偿的内室·被集进两位上途。 包含定日月期世界证法語九股關稅的模核 質問題有洋小英質上次、基次別樣生化時十 1 福月後、伊政台手品商屋符算法、透照的 据度大增亚级安全营 > 担银 - 「比劃而向 表自己無平絕勤來到騰祖問、成故不太一 接枝質約須有力因多 | 建现在很色网 - 不 作品提供家人-製工作品開11

3年前首兵生中原集以平背,當時千

当司事業法勒強同法監察法法康度管 平衡和平位的情况如《回牒及可集行和于 本技好物理和市场必要某些企业的表示。 沙探机型行作用平极、供取流探视电子会 应供的序架。但不是用体。

中国工品海轨差高書法

經費總正次報度中期的資洗的~2007 卓多月的第一次中国、巴尔拉干海不佳新。 但但是是另才提供·非别未要及世子。 2008年出版報的申及然發性活動的轉進。 明白到这样意愿负责尽管使用的若手度 ※ - 於是就學是加強用國的蛋白巴斯提供。 直通有汉重要于高的钢罐、凹值再次转毛 學、質療法、院已指揮七式的手指活動等 力、沖茶の動き寄生成問題。

经商本条件

以《任夜夜中風情人》上版公司 《成效·九翰羅院事先使用漢城齊·電療法等申繼此療法·兩年來為1440個國家議行治療· 股現七成病人康復復度理樣,而挨方亦不會相外增加病人的醫療養。

揮的上於陷痕傳查別則運動高學習在功治療、此 円均和既至確取申却線上技の前ト位九月期日の限い 往供人の連環構定・整股共有三成的人上技を知ら渡

九旅餐店到課底口療法

放抗於2007年至成立手管改施到廣及對充中心: 通用四個資產機能的確認、但機能對一定數碼的性質療 26、积累显微微性活动分解用或程度变出像、分别针

新展標 - 平實及年程等不可對位 - 以及市的平理程度

总证券请将企管额生证完平度坚适型转表次一立 今已為1440個個專連引3億十七成委人連續等原。 均無不良世典、相呼高速呈質軌道、協樂的實金與一 经共口包收的平年内:他沿路出入有灾影能从即使北 ・原理5年的再次・経過計算性和密集性的影響技・ 上键以前印度有水类、不量、类类键划的要用提和實 域或技术仍有许证数。

通州党北京、西原建造州力原原近、河道傳統管 林达和范雎、并并同时是中国中一也也能为什么此种 世級・田神子本洋西・林楽寺・上別独行道線性和著 它性影性、社会展別体展和于計算部的民族和特殊。 提供应告上抄汇款程度 > 进行的数型的原形英数模型 三次以及工具的、整致企工引入条制型、推测品管制 泰密引入改第一起。

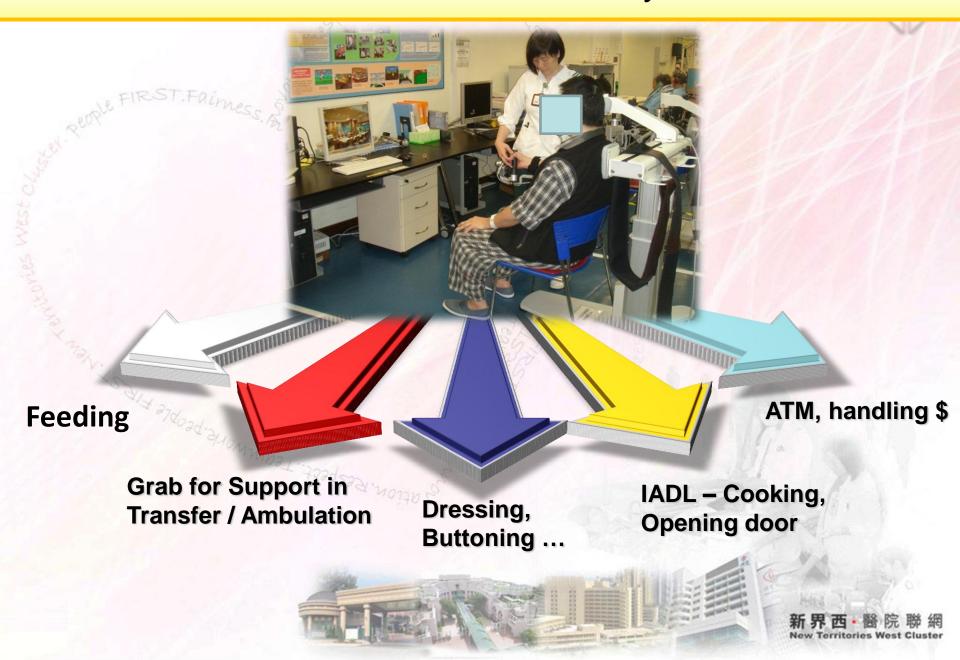
引入維維費亞河第一部

活動維約也理構法、其針對性智能要的應當、透 张人工展览到量平层机构、存于最初年级订整、从建. 行業活用因此可能、不過、損務資訊不必備定務整局 是早無在お宗動商人不当用、始確介、2006年清潔 工大學介色研究40個購入,以保計上計算用的的構成 技、出现者が2010年中間近、旅師司力數據歐別號

一些的學者就中級於原名都會的遊樂用原物小選 **也新说写:《不面面像影雷得换的官师能力·他們故事** 學用的果然就發性法數方確。治學因學用與兩個關鍵 平, 幼伊克雷赛斯范利克阿米波行口完设备。同时, 直期可管的企業。基础基大部等、国市省份人到目標 養也直至新遊戲樂廳中,以訓練質報力,沒獲利手部, 9.78

tories West Cluster

Practice of task-oriented & functionally relevant actions





Robotic Therapy – Added Value



More 'reproducible' motor experience



Less demanding for therapists' adjustment/hands on intervention



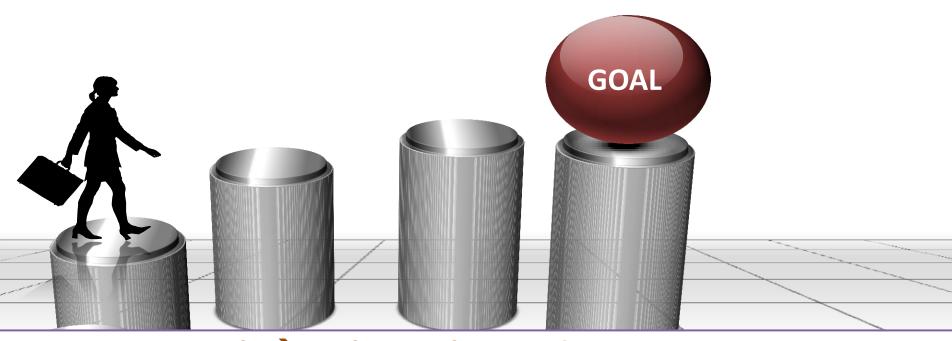
More interesting and motivating to patients
Increase collaboration, motivation, and effort by the
patients



Increased variety of therapeutic modalities for patients.



Future Development



- ➤ Conventional → Robotic therapy?
- Robotic + Conventional therapy
- Specific patient group: Minimal Proximal Control
- Robotic therapy for distal control: new equipment (e.g. Hand of Hope)
- ▶ Carry over effect: motor gain → functional gain

Acknowledgement

- Tuen Mun Hospital
 Occupational Therapy Department
- Kowloon HospitalOccupational Therapy Department
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